Changing system for component parts container
Survey of functions

Unloading area with robot

Robot cell

Container changing system in which the full container are led to the robot and the empty containers are transported to the removal.

Charging area with fork lift

Driveway
Constructional Design

Positioning axis top

Positioning axis bottom

Lift
Sequence 1

The full container is traversed into the operating position and locked.
The empty container is lifted by the lift by 1,200 mm.
The empty container is moved to the right side and simultaneously a container filled with component parts moves below to the left side and is locked in this position.
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